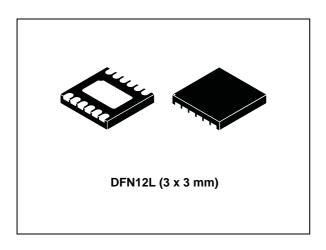
# **STOD1317B**



# 170 mA 13 V, high efficiency boost converter + LDO

Datasheet - production data



#### **Features**

- Operating input voltage range from 2.6 V to 4.8 V
- ±1% output voltage tolerance
- Low output ripple
- True-shutdown
- · Short-circuit protection
- Digital low power function
- Very high efficiency at light load thanks to pulse skipping operation
- Very fast line and load transients
- 1.2 MHz switching frequency
- 1 µA max. quiescent current
- DFN12L (3 x 3 x 0.8 mm)

# **Applications**

- Single rail AMOLED display
- Cellular phones
- · Battery powered equipment

#### **Description**

The STOD1317B is a fixed frequency, high efficiency, boost DC-DC converter with cascaded LDO able to provide output voltages ranging from 6 V to 13 V starting with an input voltage from 2.6 V to 4.8 V. The device is designed to supply loads that are very sensitive to output ripple such as AMOLED display panels. A dedicated LDO is able to suppress any ripple and noise coming out from the DC-DC converter. The LDO works with a constant drop in order to maintain high efficiency in the whole operating range. The low R<sub>DSon</sub> Nchannel and P-channel MOSFET switches are integrated and contribute to achieving high efficiency. The true-shutdown feature allows physical disconnection of the battery from the load when the device is in shutdown mode. The control technique is able to maintain efficiency higher than 85% at light loads and higher than 80% at full load. The device includes soft-start control, inrush current limiter, thermal shutdown and inductor peak current limit. The STOD1317B is packaged in DFN12L (3 x 3 x 0.8 mm) height.

**Table 1. Device summary** 

Order code	Order code Marking		Packaging
STOD1317BTPUR	1317B	DFN12L (3 x 3 mm)	3000 parts per reel

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STOD1317B Schematic

### 1 Schematic

STODO1317B VOUT

EN = STODO1317B VOUT

PGND GND FB

R1 = R2

Figure 1. Application schematic

Table 2. Typical external components

Comp.	Manufacturer	Part number	Value	Ratings	Size
C <sub>IN</sub>	MURATA Taiyo Yuden TDK	GRM219R61A106KE44 LMK212BJ106KD-T C1608X5R0J106	10µF	±10%, X5R, 10V ±10%, X5R, 10V ±10%, X5R, 6.3V	0805 0805 0603
C <sub>MID</sub>	MURATA TDK	GRM219R61C475KE15 C2012X5R1C475	4.7µF	±10%, X5R, 16V ±10%, X5R, 16V	0805 0805
C <sub>OUT</sub>	MURATA TDK	GRM219R61C475KE15 C2012X5R1C475	4.7µF	±10%, X5R, 16V ±10%, X5R, 16V	0805 0805
L <sup>(1)</sup>	CoilCraft TDK DASTEK	LPS4012-472ML VLS252012T-4R7MR81 PNL3008-4R7M	4.7µH	$\pm 20\%$ , curr. 1.7A, resist. 0.175Ω $\pm 20\%$ , curr. 1.3A, resist. 0.338Ω $\pm 20\%$ , curr. 0.9A, resist. 0.280Ω	4.0 x 4.0 x 1.2 2.5 x 2.0 x 1.2 3.1 x 3.1 x 0.8
R1			kΩ		0402
R2			kΩ		0402

Inductor used for the typical application conditions. Inductance values ranging from 3.3 μH to 6.8 μH can be used together with the STOD1317B. A minimum saturation current of 1.2 A must be ensured to support 170 mA at 2.6 V in full range.

Note: All the above components refer to a typical application. Operation of the device is not limited to the choice of these external components.

Schematic STOD1317B

Figure 2. Block schematic

STOD1317B Pin configuration

# 2 Pin configuration

Figure 3. Pin configuration (top view)

Table 3. Pin description

Pin name	Pin number	Description
VMID	1	Step-up output voltage
VOUT	2	LDO output voltage
VO_SET	3	LDO output voltage set
GND	4	Analog ground
FB	5	Feedback voltage
EN	6	Enable pin. Connect this pin to GND or a voltage lower than 0.4V to shut down the IC. A voltage higher than 1.2V is required to enable the IC
NC	7	Not connected
VIN	8	Supply voltage
PGND	9, 10	Power ground
LX	11, 12	Switch pin. Inductor connection to the internal switches
Exposed PAD		Internally connected to PGND

Maximum ratings STOD1317B

# 3 Maximum ratings

**Table 4. Absolute maximum ratings** 

Symbol	Parameter	Value	Unit
V <sub>IN</sub>	Supply voltage	-0.3 to +7.0	V
LX	Switching node	-0.3 to +16	V
V <sub>OUT_SET</sub>	LDO output voltage set	16	V
V <sub>OUT</sub>	Output voltage	-0.3 to +16	V
EN	Logic pin	-0.3 to 4.6	V
FB	Feedback pin	-0.3 to +2.5	V
ESD	Machine model	±200	V
ESD	Human body model	±2000	V
T <sub>AMB</sub>	Operating ambient temperature	-40 to 85	°C
T <sub>J</sub>	Maximum operating junction temperature	+150	°C
T <sub>STG</sub>	Storage temperature	-65 to 150	°C

Note:

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Absolute maximum ratings are those values beyond which damage to the device may occur. Functional operation under these conditions is not implied.

Table 5. Thermal data

Symbol	Parameter	Value	Unit
R <sub>thJA</sub>	Thermal resistance junction-ambient	49.1	°C/W
R <sub>thJC</sub>	Thermal resistance junction-case (FR-4 PCB)	4.216	°C/W

# 4 Electrical characteristics

 $T_J$  = 25 °C,  $V_{IN}$  = 3.7 V,  $V_{OUT}$  = 10 V,  $C_{IN}$  = 2 x 10  $\mu\text{F},~C_{MID}$  = 2 x 4.7  $\mu\text{F},~C_{OUT}$  = 3 x 4.7  $\mu\text{F},~C_{OUT}$  = 4 x 4.7  $\mu\text{F$ 

**Table 6. Electrical characteristics** 

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit
General sec	etion				•	•
V <sub>IN</sub>	Operating power input voltage range		2.6	3.7	4.8	V
lq	Shutdown mode	Shutdown mode, V <sub>EN</sub> =GND		0.5	1	μΑ
	No switching	V <sub>EN</sub> =V <sub>IN</sub> =3.7V, V <sub>FB</sub> =1.3V		1	1.5	mA
V <sub>UVLO</sub>	Undervoltage lockout threshold	V <sub>IN</sub> rising		2.4	2.5	
		V <sub>IN</sub> falling	2.1	2.2		V
f <sub>SW</sub>	Switching frequency		1	1.2	1.35	MHz
I <sub>PK</sub>	Switch current limitation		1.6	2	2.4	Α
Output volta	age (V <sub>OUT</sub> )					
V <sub>FB</sub>	Feedback voltage	T <sub>A</sub> =25°C	1.08	1.2	1.32	V
$\Delta V_{FB}$	Accuracy	-40°C <t<sub>A&lt;85°C</t<sub>	1.02		1.38	V
V <sub>OUT</sub>	Output voltage range		6	10	13	V
ΔV <sub>LINE/LOA</sub> D	Total line/load static variation (1)	T <sub>A</sub> =25°C; V <sub>IN</sub> =2.6V to 4.8V; I <sub>OUT</sub> =5mA to 170mA		30	40	mV
V <sub>OUT</sub> RIPPLE	Output voltage ripple	V <sub>IN</sub> =3.7V, V <sub>OUT</sub> =10V, I <sub>OUT</sub> =10mA			30	mV
V <sub>OVP</sub>	Overvoltage protection	V <sub>FB</sub> =0	14	15	16	V
I <sub>LKFB</sub>	FB pin leakage current	V <sub>FB</sub> =5V to 13V			1	μΑ
VMID	Step-up output voltage regulation		V <sub>OUT</sub> + 0.38	V <sub>OUT</sub> + 0.56	V <sub>OUT</sub> + 0.7	V
Logic input	s					
V <sub>IL</sub>	EN low-level input voltage				0.4	V
V <sub>IH</sub>	EN high-level input voltage		1.2			V
I <sub>LK-I</sub>	EN input leakage current	V <sub>EN</sub> =V <sub>IN</sub> =4.8V			1	μΑ
Power switch	ches	,				
	P-Channel ON resistance	I <sub>SW_P</sub> =100mA		550	900	
$R_{DSON}$	N-Channel ON resistance			400	mΩ	
I <sub>LKG-LX</sub>	LX leakage current	V <sub>IN</sub> =V <sub>LX</sub> =4.8V; V <sub>EN</sub> =0			1	μΑ

Electrical characteristics STOD1317B

Table 6. Electrical characteristics (continued)

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit	
DLP functio	DLP function						
I <sub>O_LEAK</sub>	Leakage current from load	V <sub>IN</sub> =3.7V, V <sub>EN</sub> =0, V <sub>OUT</sub> =6V (supplied by external power)		0.5	2	μА	

<sup>1.</sup> Not tested in production. This value is guaranteed by correlation with  $R_{DSON}$ , peak current limit and operating input voltage.

<sup>2.</sup> Not tested in production.

# 5 Typical performance characteristics

 $T_J$  = 25 °C,  $V_{IN}$  = 3.7 V,  $V_{OUT}$  = 10 V,  $C_{IN}$  = 2 x 10  $\mu F,$   $C_{MID}$  = 2 x 4.7  $\mu F,$   $C_{OUT}$  = 2 x4.7  $\mu F,$  L = 4.7  $\mu H,$   $V_{EN}$  = 2 V, unless otherwise specified.

Figure 4. Quiescent current vs. temperature

Figure 5. Switching frequency vs. temperature

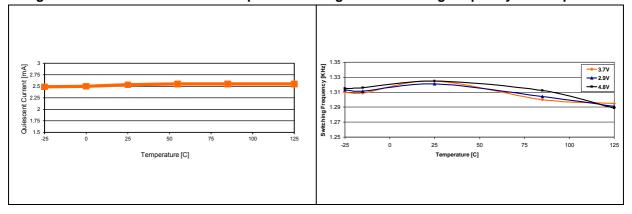


Figure 6. Efficiency vs. output current

Figure 7. Switching frequency

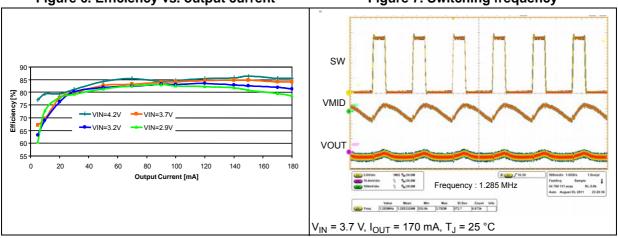


Figure 8. Soft-start inrush current

Figure 9. Feedback voltage vs. temperature

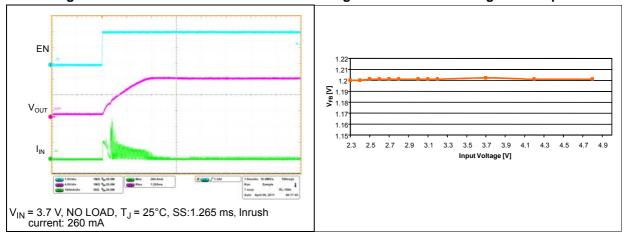
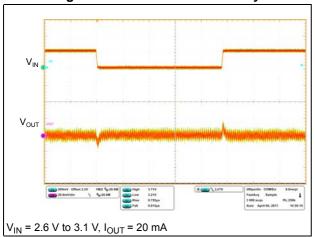




Figure 10. TDMA noise immunity



STOD1317B Detailed description

# 6 Detailed description

The STOD1317B is a high efficiency DC-DC converter which integrates a step-up and LDO power stage suitable for supplying AMOLED panels. Thanks to the high level of integration it needs only 6 external components to operate and it achieves very high efficiency using a synchronous rectification technique.

The controller uses an average current mode technique in order to obtain good stability and precise voltage regulation in all possible conditions of input voltage, output voltage and output current. In addition, the peak inductor current is monitored in order to avoid saturation of the coils.

The STOD1317B implements a power saving technique in order to maintain high efficiency at very light load and it switches to PWM operation as the load increases in order to guarantee the best dynamic performances and low noise operation.

In order to guarantee very low ripple on the output voltage, the step-up output is filtered by the LDO. There are two control loops; the LDO control loop regulates  $V_{OUT}$  in order to provide the right voltage to the output, while the boost control loop is internally set to provide and output voltage 380 mV higher than  $V_{OUT}$  in order to maintain the LDO in regulation at the minimum possible drop.

The STOD1317B avoids battery leakage thanks to the true-shutdown feature and it is self protected from overtemperature and short-circuit on the V<sub>OUT</sub> pin. Undervoltage lockout and soft-start guarantee proper operation during startup.

#### 6.1 BOOST multiple mode of operation

The boost DC-DC operates in three different modes: pulse skipping (PS), discontinuous conduction mode (DCM) and continuous conduction mode (CCM). It switches automatically between the three modes according to input voltage, output current and output voltage conditions.

#### 6.1.1 Pulse skipping operation

The STOD1317B works in pulse skipping mode when the load current is below some tens of mA. The load current level at which this way of operation occurs depends on the input and output voltage.

#### 6.1.2 Discontinuous conduction mode

When the load increases above some tens of mA, the STOD1317B enters DCM operation.

In order to obtain this type of operation the controller must avoid the inductor current going negative. The discontinuous mode detector (DMD) block senses the voltage across the synchronous rectifier and turns off the switch when the voltage crosses a defined threshold which, in turn, represents a certain current in the inductor. This current can vary according to the slope of the inductor current which depends on input voltage, inductance value, and output voltage.

#### 6.1.3 Continuous conduction mode

At medium/high output loads the STOD1317B enters full CCM at constant switching frequency mode.

Detailed description STOD1317B

#### 6.2 Enable pin

The device operates when the EN pin is set high. If the EN pin is set low, the device stops switching, all the internal blocks are turned off. In this condition the current drawn from  $V_{IN}$  is below 1  $\mu$ A in the whole temperature range. In addition, the internal switches are in OFF state so the load is electrically disconnected from the input, this avoids unwanted current leakage from the input to the load.

#### 6.3 Soft-start and inrush current limiting

After the EN pin is pulled high, or after a suitable voltage is applied to  $V_{IN}$  and EN, the device initiates the startup phase.

As a first step, the  $C_{\text{MID}}$  capacitor is charged, the P1 switch implements a current limiting technique in order to keep the charge current below 400 mA. This avoids battery overloading during startup.

After  $V_{MID}$  reaches the  $V_{IN}$  voltage level, the P1 switch is fully turned on and the soft-start procedure for the step-up is started.  $V_{OUT}$  starts to softly increase until it reaches the regulation value.

#### 6.4 Undervoltage lockout

The undervoltage lockout function avoids improper operation of the STOD1317B when the input voltage is not high enough. When the input voltage is below the UVLO threshold the device is in shutdown mode. The hysteresis of 100 mV avoids unstable operation when the input voltage is close to the UVLO threshold.

# 6.5 Overtemperature protection

An internal temperature sensor continuously monitors the IC junction temperature. If the IC temperature exceeds 150 °C, typical, the device stops operating. As soon as the temperature falls below 135 °C, typical, normal operation is restored.

# 6.6 Digital low power function

The digital low power (DLP) function allows physical disconnection of the load from the device.

STOD1317B Detailed description

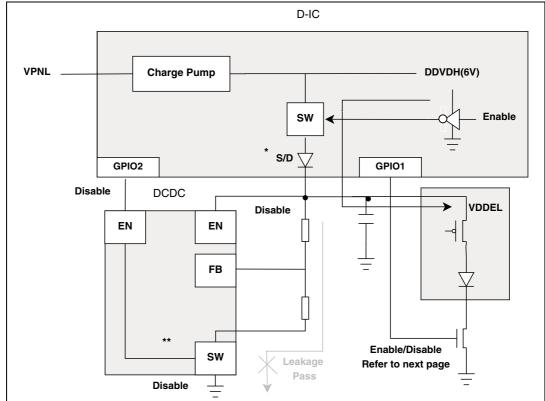


Figure 11. Digital low power function

#### Operation

- (\*) When the power IC is disabled, in order to disconnect leakage current through the feedback node, the S/W function is active.
- (\*\*) A new EN transition from low to high and/or device power-up turn off the DLP function and allow IC to work under typical conditions.

# 7 Application information

#### 7.1 External passive components

#### 7.1.1 Inductor selection

The inductor is the key passive component for switching converters.

For the step-up converter an inductance between 3.3 µH and 6.8 µH is recommended.

It is very important to select the right inductor according to the maximum current the inductor can handle in order to avoid saturation. The peak current for the step-up can be calculated as:

#### **Equation 1**

$$I_{PEAK~BOOST} = \frac{V_{MID} \times I_{OUT}}{\eta \times VIN_{MIN}} + \frac{VIN_{MIN} \times (V_{MID} - VIN_{MIN})}{2 \times V_{MID} \times fs \times L}$$

where

V<sub>MID</sub>: step-up output voltage, it is fixed internally to V<sub>OUT</sub> + 0.38 V;

I<sub>OUT</sub>: output current;

V<sub>IN</sub>: input voltage of the STOD1317B;

fs: switching frequency. Use the minimum value of 1 MHz for worst case;

η: efficiency of the step-up converter (0.80 at maximum load).

#### 7.1.2 Input and output capacitor selection

It is recommended to use ceramic capacitors with low ESR as input and output capacitors in order to filter any disturbance present in the input line and to obtain stable operation of the step-up converter and LDO. A minimum real capacitance value of 3  $\mu$ F must be guaranteed for  $C_{\text{MID}}$  and  $C_{\text{OUT}}$  in all conditions.

### 7.2 Recommended PCB layout

The STOD1317B is a high frequency power switching device so it requires a proper PCB layout in order to obtain the necessary stability and optimize line/load regulation and output voltage ripple.

The input capacitor must be as close as possible to the V<sub>IN</sub> pin.

In order to minimize the ground noise, a common ground node for power ground (PGND) and a different one for analog ground (GND) must be used. The exposed pad is connected to PGND through vias.

Grounding is fundamental to the operation of DC-DC converters; run separate ground paths for critical parts of the circuit (GND and Power GND), each connected back to a single ground point.

Separate ground lines prevent the current and noise of one component from interfering with other components. If using a ground plane, utilize "split" plane techniques to give effective grounding. Use multiple vias to decrease the trace impedance to ground.

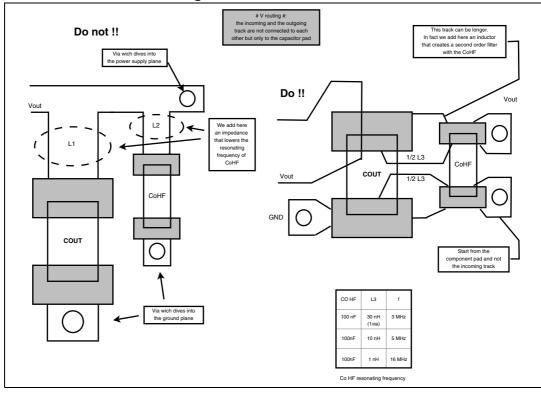


Figure 12. Ground schematic

Such isolation is necessary to prevent high-level switching currents from returning to the battery, or other power supply, through the same ground-return path as the analog signals.

If that happens, the ground path of those sensitive signals is disturbed; the high-level switching currents flowing through the ground's resistance and inductance cause the voltage along the return path to vary.

In addition to the grounding scheme, proper placement of the regulator's components is important.

Beginning a new layout, for the reasons above, it is necessary to firstly place the capacitors  $C_{\text{IN}}$ ,  $C_{\text{OUT}}$  and  $C_{\text{MID}}$  as close as possible to the related device pins.

After that, it is possible to place the inductors and the Power GND routing. Next, we can trace the GND connected through vias to the PGND near to one of the main filter capacitors.

The LDO needs a guiet ground signal in order to operate properly.

It is important to pay close attention to the routing of traces from capacitor terminals in a DC-DC converter circuit.

Large-valued low-ESR capacitors are expensive, and bad routings can cancel their performance.

A good routing, on the other hand, can lower the output noise.

Ripple is directly related to the inductor value, the capacitor ESR, the switching frequency, and so forth, but HF noise (spikes) depends on parasitic elements and the switching action. In a bad routing, parasitic inductance associated with trace lengths causes problems: In *Figure 12*, L1 brings about an increase in noise, and L2 limits the attenuation of an added HF capacitor. The solution is to bring the input trace in on one side of the capacitor pad, and the output trace out on the other side of the pad.



Figure 13. Top layer

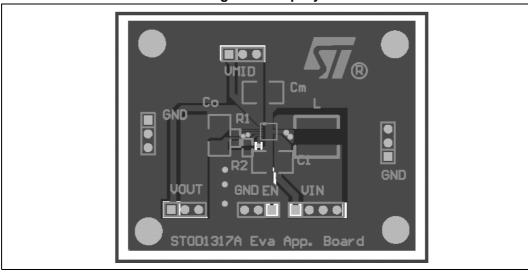
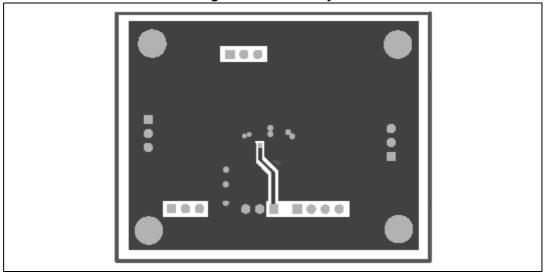


Figure 14. Bottom layer



# 8 Package mechanical data

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK<sup>®</sup> packages, depending on their level of environmental compliance. ECOPACK<sup>®</sup> specifications, grade definitions and product status are available at: <a href="https://www.st.com">www.st.com</a>. ECOPACK<sup>®</sup> is an ST trademark.

Table 7. DFN12L (3 x 3 x 0.8 mm.) package mechanical data

Dim.	mm.				
Dilli.	Min.	Тур.	Max		
А	0.70	0.75	0.80		
A1	0	0.02	0.05		
A3		0.20			
b	0.18	0.25	0.30		
D	2.85	3	3.15		
D2	1.87	2.02	2.12		
E	2.85	3	3.15		
E2	1.06	1.21	1.31		
е		0.45			
L	0.30	0.40	0.50		

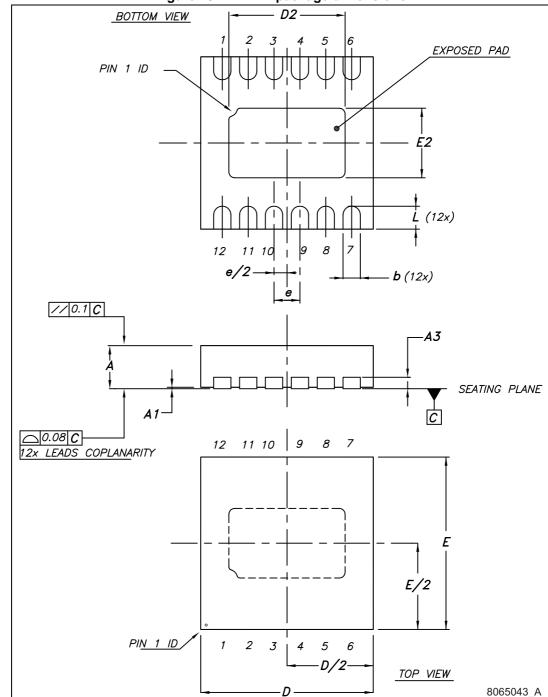
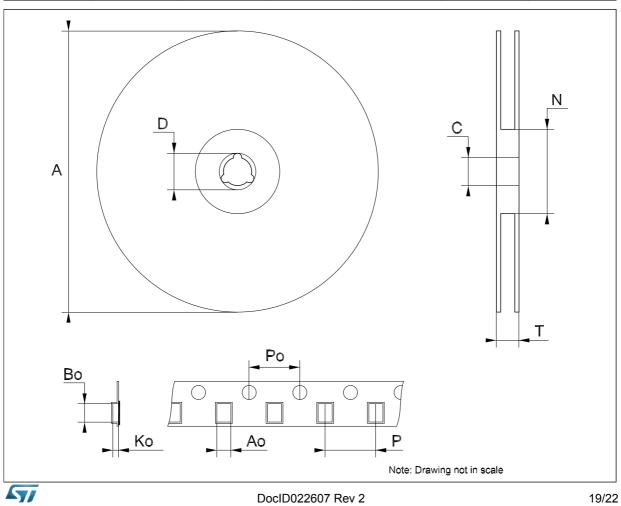


Figure 15. DFN12L package dimensions

DIM.		mm.			inch	
DIIVI.	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
А			330			12.992
С	12.8		13.2	0.504		0.519
D	20.2			0.795		
N	99		101	3.898		3.976
Т			14.4			0.567
Ao		3.3			0.130	
Во		3.3			0.130	
Ko		1.1			0.043	
Ро		4			0.157	
Р		8			0.315	



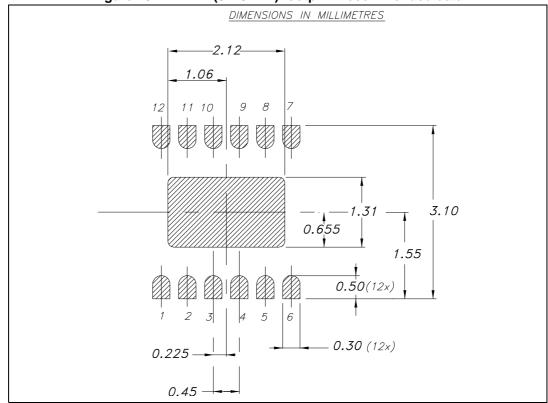


Figure 16. DFN12L (3 x 3 mm) footprint recommended data

STOD1317B Revision history

# 9 Revision history

Table 8. Document revision history

Date	Revision	Changes
19-Dec-2011	1	Initial release.
11-Apr-2013	2	Updated:  — Package mechanical data <i>Table 7 on page 17</i> and <i>Figure 15 on page 18</i> .

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